

AMSI Summer School: Hyperbolic Knot Theory Quiz

Problem 1 (Algebra). Let $\mathrm{SL}(2, \mathbb{C})$ denote the set of 2×2 matrices with complex coefficients and determinant one. That is, elements have the form $\begin{pmatrix} a & b \\ c & d \end{pmatrix}$ where a, b, c, d lie in \mathbb{C} and $ad - bc = 1$.

- Prove that the product of two matrices in $\mathrm{SL}(2, \mathbb{C})$ is in $\mathrm{SL}(2, \mathbb{C})$. Prove that the inverse of a matrix in $\mathrm{SL}(2, \mathbb{C})$ is in $\mathrm{SL}(2, \mathbb{C})$.
- $\mathrm{SL}(2, \mathbb{C})$ acts on $z \in \mathbb{C} \cup \{\infty\}$ as follows:

$$Az = \begin{pmatrix} a & b \\ c & d \end{pmatrix} (z) \mapsto \frac{az + b}{cz + d}$$

If $z = \infty$ we take this to be $\frac{a}{c}$. Show that the action of A and $-A$ is identical. Thus we will often consider $\mathrm{PSL}(2, \mathbb{C}) = \mathrm{SL}(2, \mathbb{C}) / \sim$ where $A \sim -A$.

- Show that an element A in $\mathrm{PSL}(2, \mathbb{C})$ that is not the identity either fixes one or two points in $\mathbb{C} \cup \{\infty\}$. Prove that if it has exactly one fixed point, its trace is ± 2 .

Problem 2 (Distance function). Recall that a function $d: X \times X \rightarrow [0, \infty)$ is called a distance function if it satisfies:

- (Symmetry) $d(x, y) = d(y, x)$ for all $x, y \in X$
- (Nondegeneracy) $d(x, y) = 0$ if and only if $x = y \in X$
- (Triangle inequality) $d(x, z) \leq d(x, y) + d(y, z)$ for all $x, y, z \in X$.

Prove that the usual Euclidean distance function $d_E: \mathbb{R}^n \times \mathbb{R}^n \rightarrow [0, \infty)$ satisfies this definition, where d_E is given by:

$$d_E((x_1, \dots, x_n), (y_1, \dots, y_n)) = \left(\sum_{i=1}^n (x_i - y_i)^2 \right)^{1/2}$$

Problem 3 (Open set). Suppose X admits a distance function $d: X \times X \rightarrow [0, \infty)$. For any $x \in X$, the ball of radius $\delta > 0$ centred at x is defined to be the set:

$$B(x, \delta) = \{y \in X \mid d(x, y) < \delta\}$$

A set $V \subset X$ is said to be *open* if for every $x \in V$, there exists $\delta > 0$ such that $B(x, \delta) \subset V$. It is *closed* if its complement is open.

Prove that if $\{V_\alpha\}_{\alpha \in \mathcal{A}}$ is a collection of open sets in X , then the union $\bigcup_{\alpha \in \mathcal{A}} V_\alpha$ is also open. Prove that if $\{V_i\}_{i=1}^k$ is a finite collection of open sets in X then the intersection $\bigcap_{i=1}^k V_i$ is open.

Problem 4 (Cauchy sequences). Again let X be a space with a distance function d . Recall that a *Cauchy sequence* is a sequence $\{x_n\}$ such that for any $\epsilon > 0$, there exists $N \in \mathbb{Z}$ such that $n, m \geq N$ implies $d(x_n, x_m) < \epsilon$.

- Prove that if $\{x_n\}$ is a convergent sequence then it is a Cauchy sequence.
- Let X be the rational numbers \mathbb{Q} with the usual distance function inherited from \mathbb{R} . Show that there exists a Cauchy sequence in X that does not converge in X .

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Problem 5 (Homotopy of curves). A *curve* in a space X is a continuous map $\gamma: [0, 1] \rightarrow X$.

Suppose γ_0 and γ_1 are curves, and suppose $\gamma_0(0) = \gamma_1(0)$, and $\gamma_0(1) = \gamma_1(1)$. We say the two curves γ_0 and γ_1 are *homotopic* if there exists a continuous map $H: [0, 1] \times [0, 1] \rightarrow X$ such that $H(t, 0) = \gamma_0(t)$ and $H(t, 1) = \gamma_1(t)$. They are *homotopic rel endpoints* if in addition, $H(0, s) = \gamma_0(0) = \gamma_1(0)$ and $H(1, s) = \gamma_0(1) = \gamma_1(1)$. The map H is called a *homotopy*. These notions give relations on the set of curves in X , namely homotopy of curves and homotopy of curves rel endpoints.

Prove that homotopy of curves is an equivalence relation. Similarly, homotopy of curves rel endpoints is an equivalence relation.

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Solution.[Problem 1 Algebra] (a) The product of two matrices in $SL(2, \mathbb{C})$ and the inverse are given as follows:

$$\begin{pmatrix} a & b \\ c & d \end{pmatrix} \cdot \begin{pmatrix} e & f \\ g & h \end{pmatrix} = \begin{pmatrix} ae + bg & af + bh \\ ce + dg & cf + dh \end{pmatrix}, \quad \begin{pmatrix} a & b \\ c & d \end{pmatrix}^{-1} = \begin{pmatrix} d & -b \\ -c & a \end{pmatrix}$$

All entries are in \mathbb{C} . The determinant of the product is

$$(ae + bg) * (cf + dh) - (af + bh)(ce + dg) = (ad - bc)(ef - gh) = 1$$

The determinant of the inverse is $ad - bc = 1$.

(b) Note $-A$ adjusts the matrix A by multiplying all entries by -1 . For the action on $\mathbb{C} \cup \{\infty\}$, this has the effect of multiplying both entries in the numerator by -1 and both entries in the denominator by -1 . Hence they cancel, and the action agrees with that of A .

(c) We find the fixed points of the action of $PSL(2, \mathbb{C})$ on $\mathbb{C} \cup \{\infty\}$. Suppose

$$\frac{az + b}{cz + d} = z. \text{ Then } az + b = cz^2 + dz$$

Thus z is a root of the polynomial $cz^2 + (d - a)z - b$ with complex coefficients. The roots are given by the quadratic formula:

$$z = \frac{(a - d) \pm \sqrt{(d - a)^2 + 4cb}}{2c}$$

There will be two roots, corresponding to two fixed points, unless the discriminant $(d - a)^2 + 4bc$ is zero, in which case there will be one root.

If the discriminant is zero, we have $d^2 - 2da + a^2 + 4bc = 0$. Note the left hand side of this equation is $d^2 + a^2 - 4(ad - bc) + 2ad$, or $(d + a)^2 - 4$. So there is one root if and only if $(d + a)^2 = 4$, or $d + a = \pm 2$.

Solution.[Problem 2 Distance function] Symmetry follows from the fact that

$$(x_i - y_i)^2 = (y_i - x_i)^2$$

so $d(x, y) = d(y, x)$.

We have $d(x, y) = 0$ if and only if $\sum (x_i - y_i)^2 = 0$. Since each term in the sum is nonnegative, this is zero if and only if each $(x_i - y_i) = 0$, or if and only if $(x_1, \dots, x_n) = (y_1, \dots, y_n)$.

For the triangle inequality, for each i we have

$$(x_i - z_i)^2 = (x_i - y_i + y_i - z_i)^2 \leq (x_i - y_i)^2 + (y_i - z_i)^2$$

Solution.[Problem 3 Open set] To show the union is open, we need to show that for every point x in the union, there is $\delta > 0$ such that the ball $B(x, \delta)$ lies inside the union. But if x is in the union, then x must be in one of the V_α . Because V_α is open, there exists $\delta_\alpha > 0$ such that $B(x, \delta_\alpha) \subset V_\alpha$. Since $V_\alpha \subset \bigcup_\beta V_\beta$, the ball $B(x, \delta_\alpha)$ also lies in the union.

For the intersection, suppose $x \in \bigcap V_i$. Then $x \in V_i$ for each i . Thus there exist $\delta_1, \dots, \delta_k$ such that each $\delta_i > 0$ and $B(x, \delta_i) \subset V_i$. Let δ be the minimum of the δ_i . Then $\delta > 0$ and $B(x, \delta) \subset B(x, \delta_i) \subset V_i$ for $i = 1, \dots, k$. Thus $B(x, \delta) \subset \bigcap V_i$.

Solution.[Problem 4 Cauchy sequences] (a) Fix $\epsilon > 0$. The fact that $\{x_n\}$ is a convergent sequence means that there exists $x \in X$ such that for any $\epsilon > 0$, there exists an integer N such

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that $n \geq N$ implies $x_n \in B(x, \epsilon/2)$. Then for $n, m \geq N$,

$$d(x_n, x_m) \leq d(x_n, x) + d(x, x_m) < \epsilon.$$

Here the first inequality is by the triangle inequality, and the second follows from the fact that x_n and x_m lie in $B(x, \epsilon/2)$.

(b) Choose a sequence of rational numbers converging to an irrational number. For example, take $\{x_n\} \subset \mathbb{Q}$ converging to $\sqrt{2}$ in \mathbb{R} . Then for any $\epsilon > 0$, as above there exists N such that $n, m \geq N$ implies $d(x_n, x_m) \leq d(x_n, \sqrt{2}) + d(\sqrt{2}, x_m) < \epsilon$, so this is a Cauchy sequence. However, it cannot converge to any point in \mathbb{Q} . For if $y \in \mathbb{Q}$, then there exists $\delta > 0$ such that $d(y, \sqrt{2}) > \delta/2$. Then for sufficiently large N , x_n lies in $B(\sqrt{2}, \delta/2)$, which is disjoint from the ball $B(y, \delta/2)$. Thus $\{x_n\}$ cannot converge to $y \in \mathbb{Q}$.

Solution.[Problem 5 Homotopy of curves] We need to show homotopy is reflexive, symmetric, and transitive.

Reflexive: For $\gamma: [0, 1] \rightarrow X$, we define $H: [0, 1] \times [0, 1] \rightarrow X$ to be $H(t, s) = \gamma(t)$. Then this is continuous because γ is continuous, and $H(t, 0) = H(t, 1) = \gamma(t)$. Note the same argument applies for homotopy rel endpoints.

Symmetric: If γ_0 is homotopic to γ_1 , then there exists a continuous map $H: [0, 1] \times [0, 1] \rightarrow X$ with $H(t, 0) = \gamma_0(t)$ and $H(t, 1) = \gamma_1(t)$. Then define $\bar{H}: [0, 1] \times [0, 1] \rightarrow X$ by $\bar{H}(t, s) = H(t, 1 - s)$. Then $\bar{H}(t, 0) = H(t, 1) = \gamma_1(t)$ and $\bar{H}(t, 1) = H(t, 0) = \gamma_0(t)$. Thus homotopy is symmetric. Observe that if $H(0, s) = \gamma_0(0) = \gamma_1(0)$ for all s , then $\bar{H}(0, s) = \gamma_0(s) = \gamma_1(s)$ for all s , and similarly for $\bar{H}(1, s)$. So symmetry holds rel endpoints.

Transitive: Suppose γ_0 is homotopic to γ_1 and γ_1 is homotopic to γ_2 , via homotopies H and G . Then let $F: [0, 1] \times [0, 1] \rightarrow X$ be defined by

$$F(t, s) = \begin{cases} H(t, 2s) & \text{if } 0 \leq s \leq 1/2 \\ G(t, 2s - 1) & \text{if } 1/2 \leq s \leq 1 \end{cases}$$

Note when $s = 1/2$, $H(t, 2s) = H(t, 1) = \gamma_1(t) = G(t, 0) = G(t, 2s - 1)$, so F is continuous. Then $F(t, 0) = H(t, 0) = \gamma_0(t)$ and $F(t, 1) = G(t, 1) = \gamma_2(t)$, so F is a homotopy from γ_0 to γ_2 . Thus it is transitive.

If the homotopies H and G are rel endpoints, then so is the homotopy F . So homotopy rel endpoints is also transitive.